

dRDF: Entailment for Domain-Restricted RDF

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Alternative subtitles:

Blank nodes are fun (at least for theoreticians)

or

Blank nodes ain't THAT evil! 😊

RDF Entailment: $G_1 \models G_2$



- Does graph G_1 entail G_2 ?
- Boils down to:
“Is there a blank node renaming μ for blank nodes in G_2 such that $\mu(G_2) \subseteq G_1$ ”
- “Folklore”: Well-known to be NP-complete (cf. RDF Semantics [Hayes, 2004])
- Observation: *Blank nodes* are causing the “trouble” of making the problem intractable... ground entailment well known to be in P.

Starting point for our work:

Besides completely forbidding blank nodes...

... What else can we do to make this problem tractable?

Restrictions on RDF graphs considered in this paper:



1. **Domain-Restricted Graphs:** Restrict the domain blank nodes can range over to a finite set of objects.
2. **Graphs with Bounded Treewidth:** Restrict the graph structure of RDF graphs: bounded-treewidth (a generalization of acyclicity)

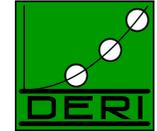
Effects:

1. ...OOPS! With *finite domains*, complexity actually jumps from NP to $\text{coNP}^{\text{NP}} = \Pi_2^{\text{P}}$ 😞
2. Not all is lost: *bounded treewidth* guarantees tractability for general entailment and coNP bound for domain-restricted graphs.

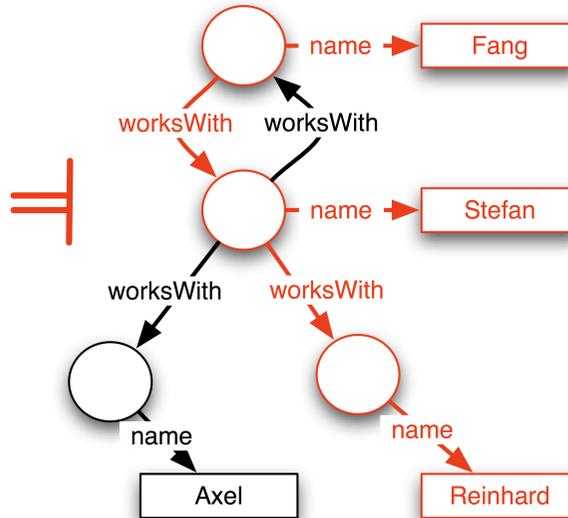
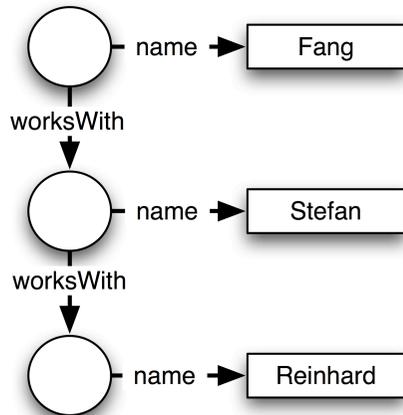
Summary:

	domain-restricted graphs	Unrestricted graphs
bounded treewidth	coNP-complete	in P 😊
unbounded treewidth	Π_2^{P} -complete	NP-complete

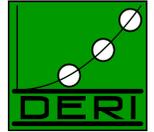
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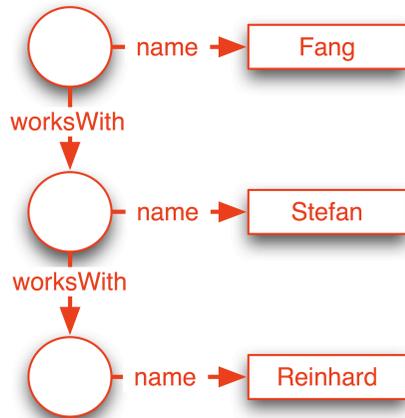
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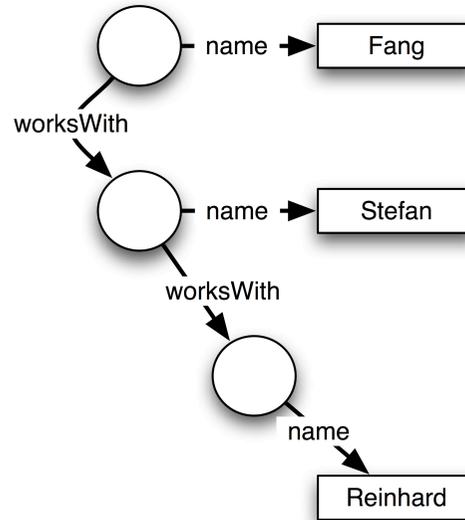
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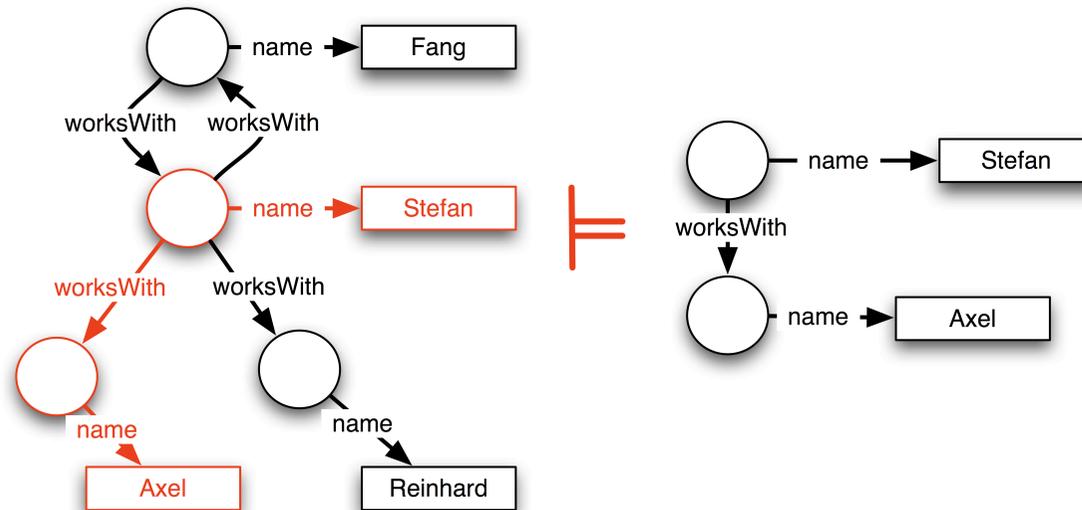
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Domain-Restricted Graphs: Example



Fang Wei

Stefan Woltran

Stefan Decker

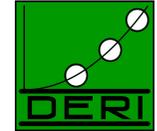
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$D_1 = \text{TUV} =$
 { :fangwei, :stefanwoltran,
 :reinhardpichler, :thomaseiter, ... }

$D_2 = \text{TUV} \cup \text{Alumni} =$
 { :fangwei, :stefanwoltran,
 :reinhardpichler, :thomaseiter,
 :axelpolleres, :manfredhauswirth, ... }

$D_3 = \text{DERI} =$
 { :stefandecker,
 :axelpolleres, :manfredhauswirth ... }

Domain-Restricted Graphs: Example



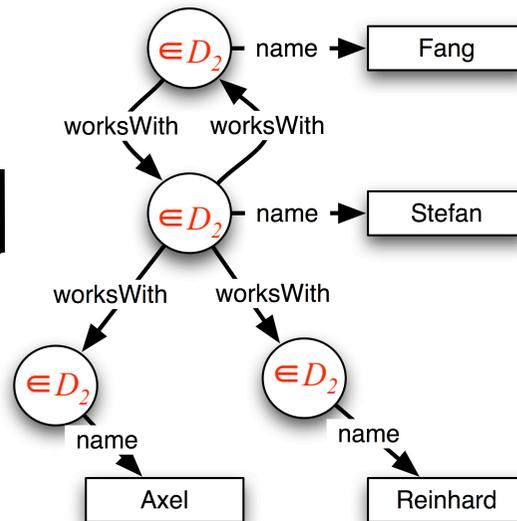
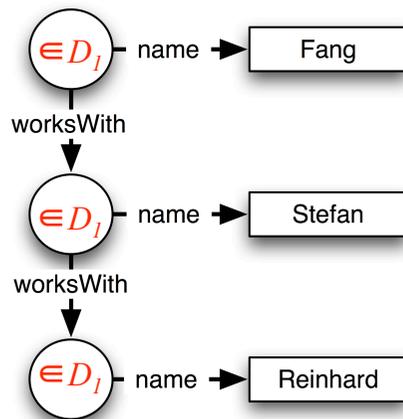
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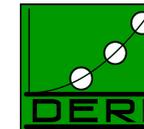
Stefan Decker

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$D_1 \subseteq D_2$

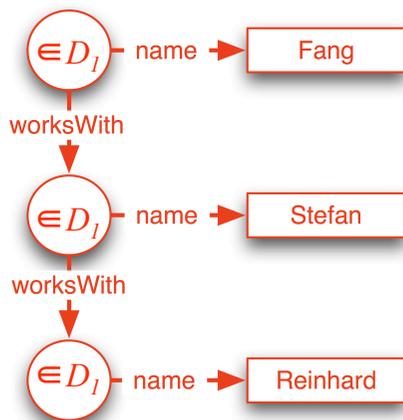


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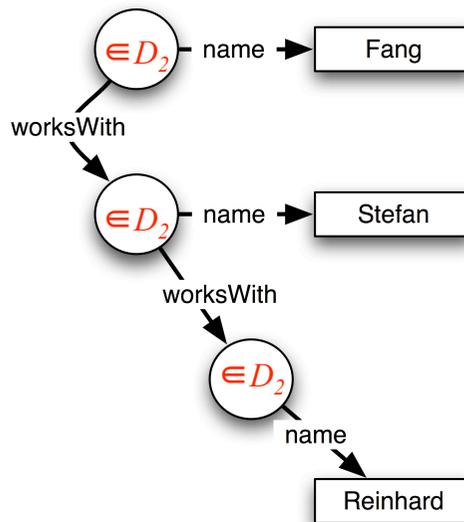


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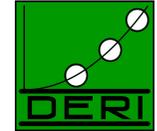
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Domain-Restricted Graphs: Example



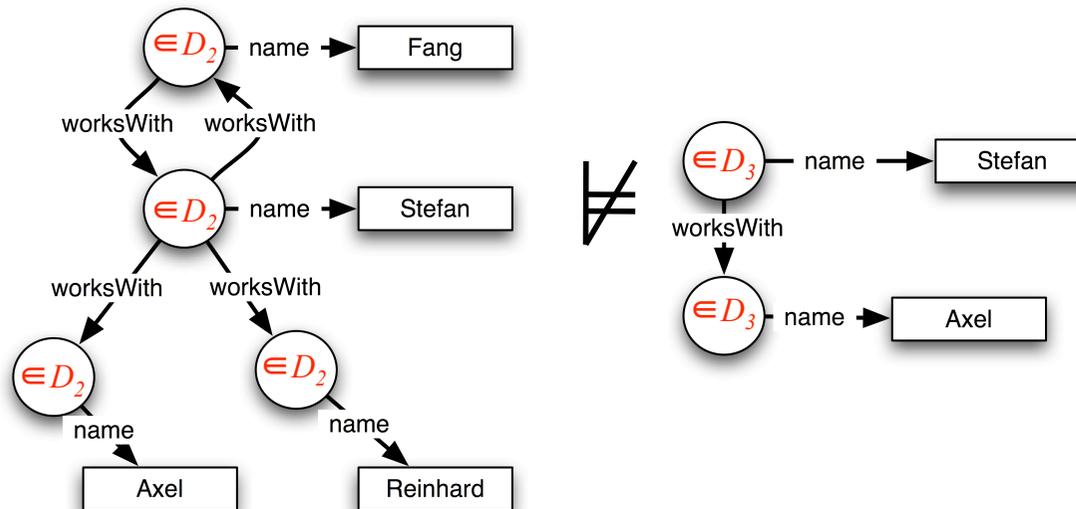
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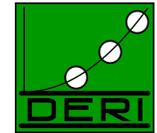
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$D_2 \not\subseteq D_3, D_3 \not\subseteq D_2$



Domain-Restricted Graphs $\langle G, D \rangle$: Definition



- Base notion in RDF semantics: RDF interpretation for a Graph G

$$I = (Res, Prop, Lit, \varepsilon, IS, IL)$$

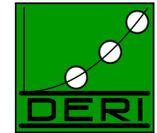
- We define the D-restriction of RDF interpretations:

$$I_D = (Res \cap D, Prop, Lit \cap D, \varepsilon, IS_{Res \cap D}, IL_{Res \cap D})$$

- Entailment for domain-restricted graphs, defined as wrt. D-restriction of RDF interpretations:

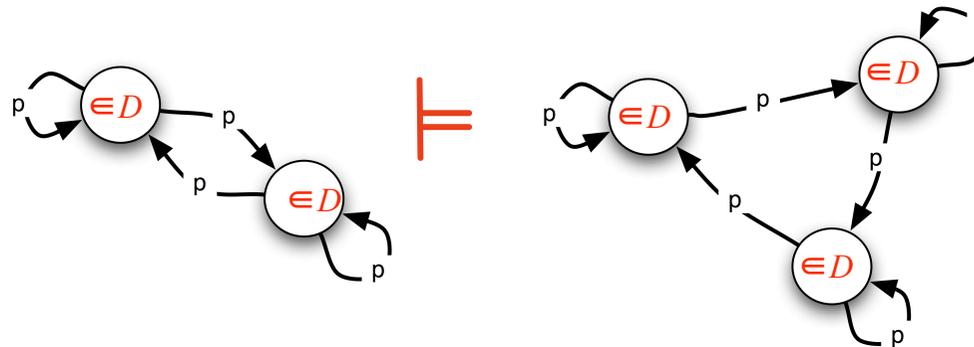
$$\langle G_1, D_1 \rangle \models \langle G_2, D_2 \rangle$$

Domain-Restricted Graphs: Properties



- $D_1 \not\subseteq D_2$ implies $\langle G_1, D_1 \rangle \not\models \langle G_2, D_2 \rangle$
- $G_1 \models G_2$ implies $\langle G_1, D \rangle \models \langle G_2, D \rangle$
- *But: Complexity of D-entailment is Π_2^p ... Uh?*

Example:
 $D = \{a, b\}$



– *Intuitively:*

More entailments by implicit equalities if $|D|$ is small enough!

Complexity proof (Ideas)



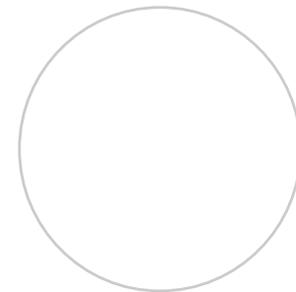
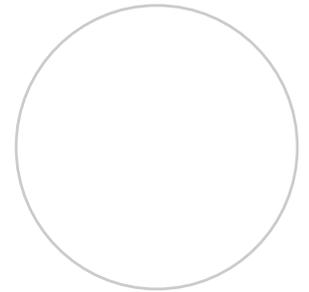
- *Membership: non-entailment in Π_2^P :*
 - *We can assume w.l.o.g. that G_1 is ground*
 - *“ $\langle G_1, D \rangle$ does not d-entail $\langle G_2, D \rangle$ ” can be decided in Σ_2^P by*
 1. *Guessing a D -interpretation such that G_1 is true*
 2. *Check that G_2 is false for all possible assignments of bnodes to elements of D*
- *Hardness proof by a reduction from a special variant of H -subsumption*, for $|D| \geq 4 \dots$ long version.*

* “total binary H -subsumption” i.e., no constants are allowed in clauses and only binary predicates, fixed finite Herbrand universe

Now how to remedy the mess we did...



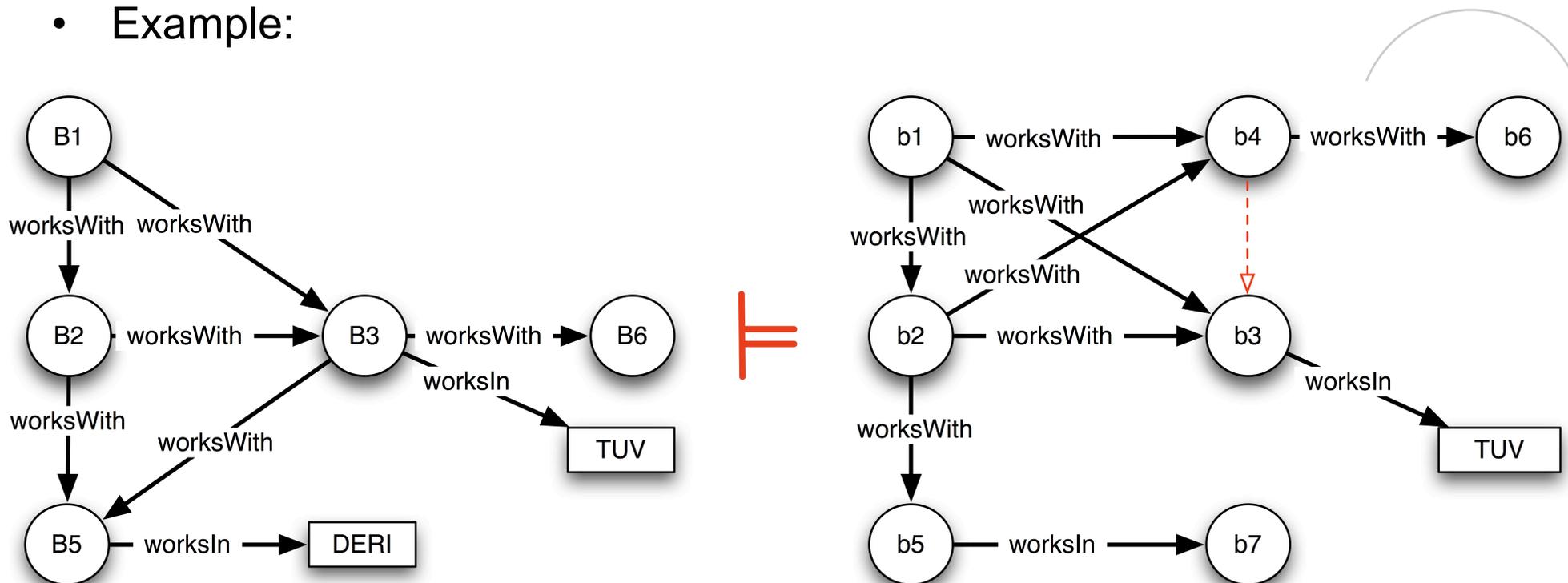
- ... we saw the first “restriction” made things more complex.
- But: ***bounded treewidth*** helps!



Bounded Treewidth for RDF graphs:



- Measure of “acyclicity”
- Roughly:
“If I can decompose the graph to a tree of hyper-edges with at most $k - 1$ nodes per edge, then the graph has treewidth k ”
- Example:

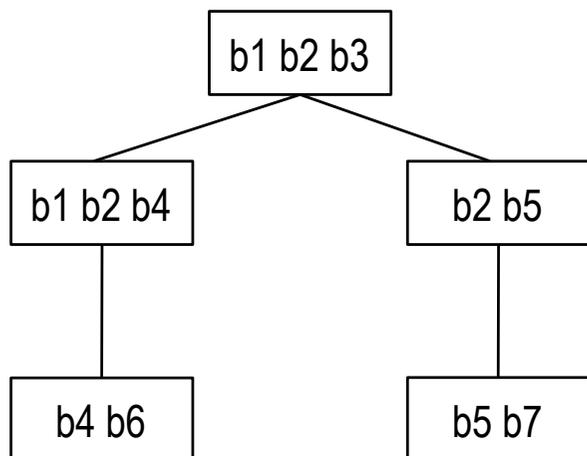


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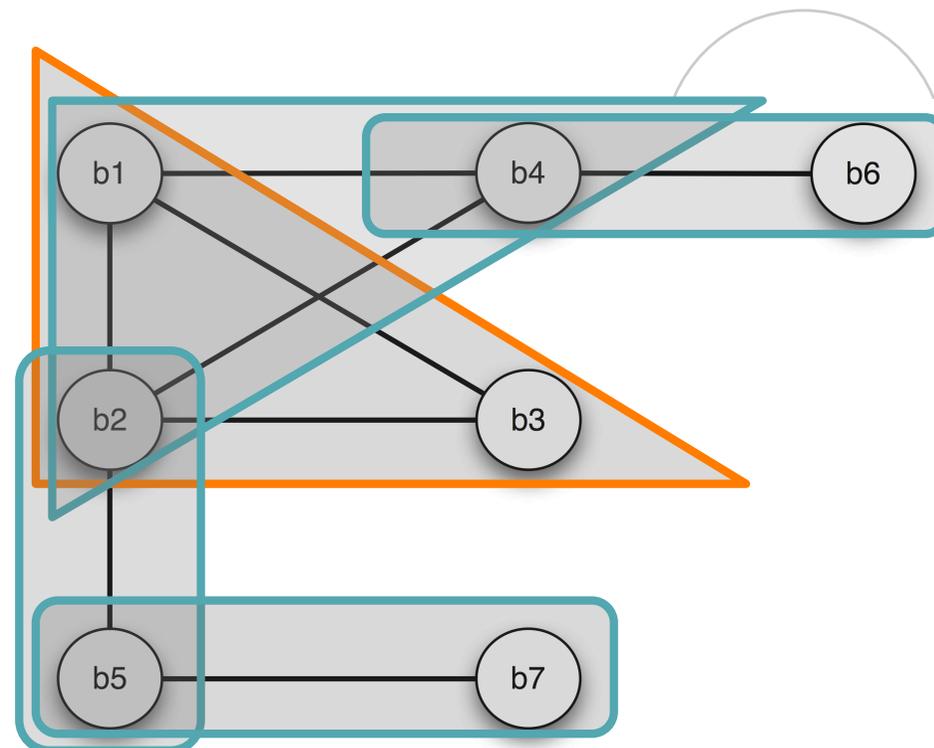


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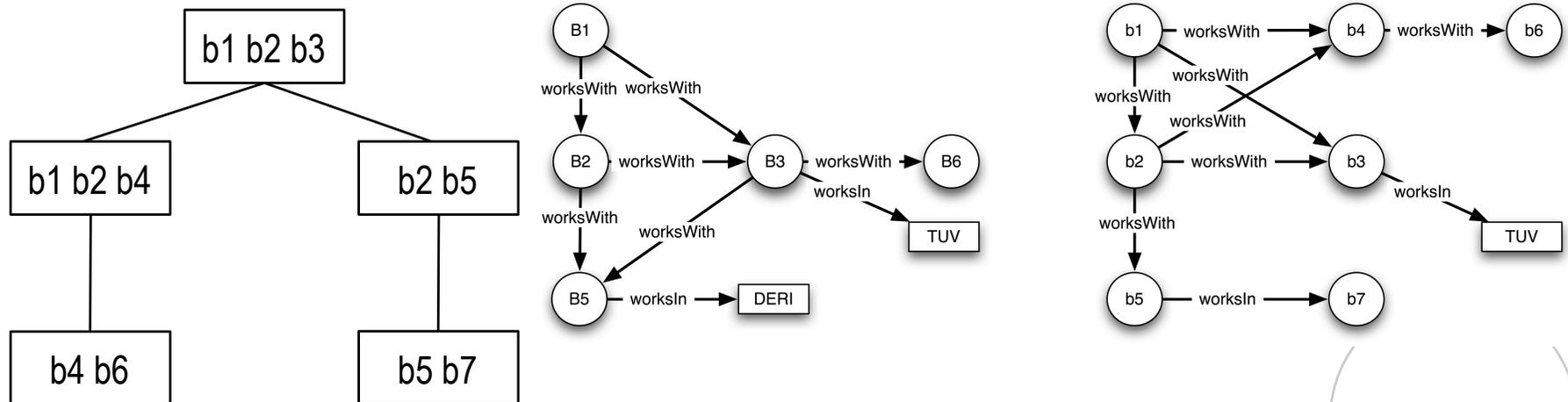
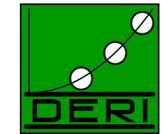
“Skeleton” relevant for tree-decomposition:



$$tw(G_2) = 2$$

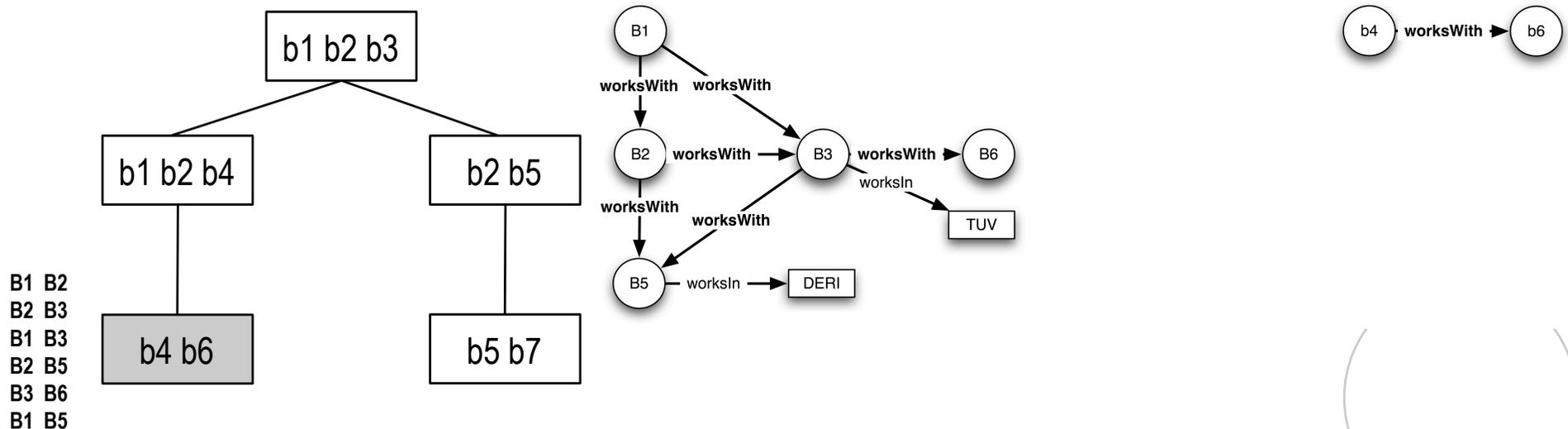
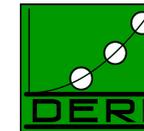


Polynomial time Algorithm for Entailment with Bounded Treewidth for G_2 (Idea):



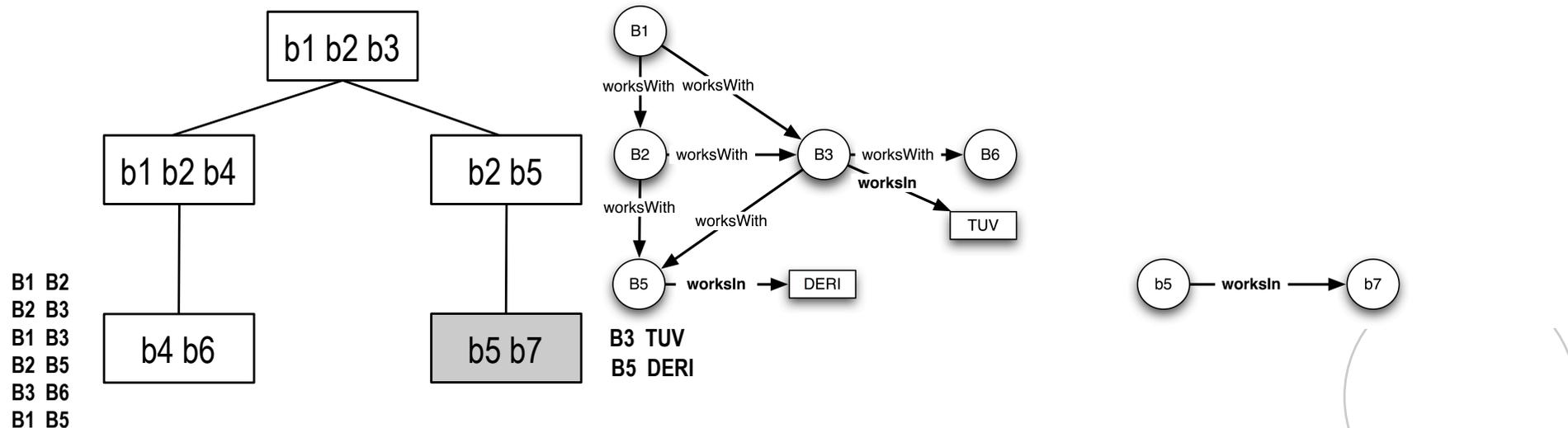
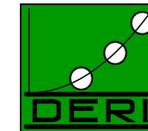
- From the decomposition, process the **induced subgraphs** “bottom-up” in a modular fashion, computing partial bnode assignments.
- When going upwards, filter allowed assignments by *semi-joins* with the assignments for the child nodes.
- If an assignment “survives” at the root, entailment holds.
- $O(n^k)$ for entailment checks per node
- $O(n^{2k})$ per semi-join
- Thus, for $|G_2| = m$ we get as upper bound: $O(m^2 + mn^{2k})$

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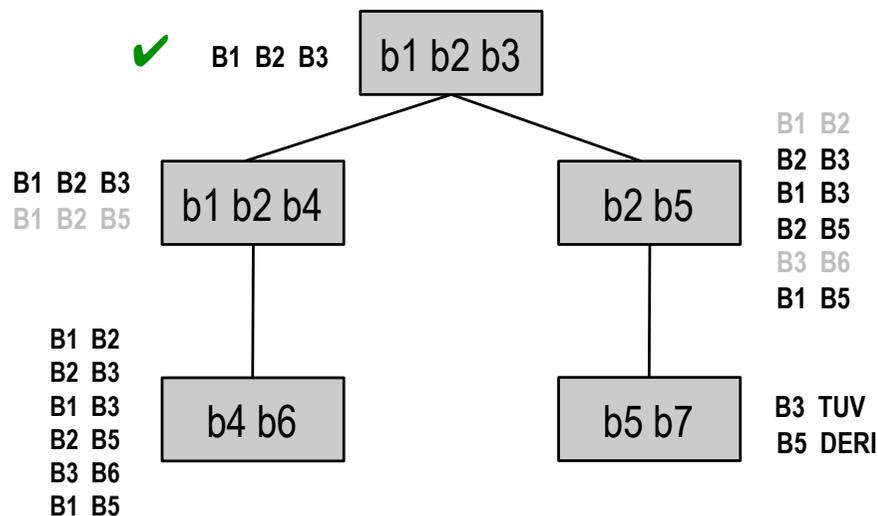
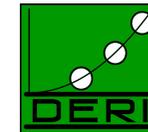
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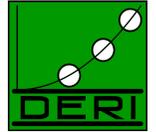
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- Thus, for $|G_2| = m$ we get as upper bound: $O(m^2 + mn^{2k})$

Now what about D-entailment with bounded treewidth?



- Overall complexity drops from Π_2^P to coNP:

Recall from above:

- “ $\langle G_1, D \rangle$ does not d-entail $\langle G_2, D \rangle$ ” can be decided in Σ_2^P by
 1. *Guessing a D-interpretation such that G_1 is true*
 2. *Check that G_2 is false for all possible assignments of bnodes to elements of D*

- Step 2. can be done in polynomial time for bounded tree-width.
- coNP-hardness still holds (proof by 3-colorability, see paper.)

Summary:



- Some form of domain-restriction may be useful for graphs on the Web...
 - ... but comes at some cost!
 - Things are not that bad unless we expect small domains (less elements than bnodes)
- Similar results for
 - enumerated classes in (fragments of) OWL?
 - entailment with finite datatypes?, etc.

➔ Future work!
- Bounded treewidth is more general than acyclicity. **Good news!** (if we don't expect graphs with large cycles among bnodes)

